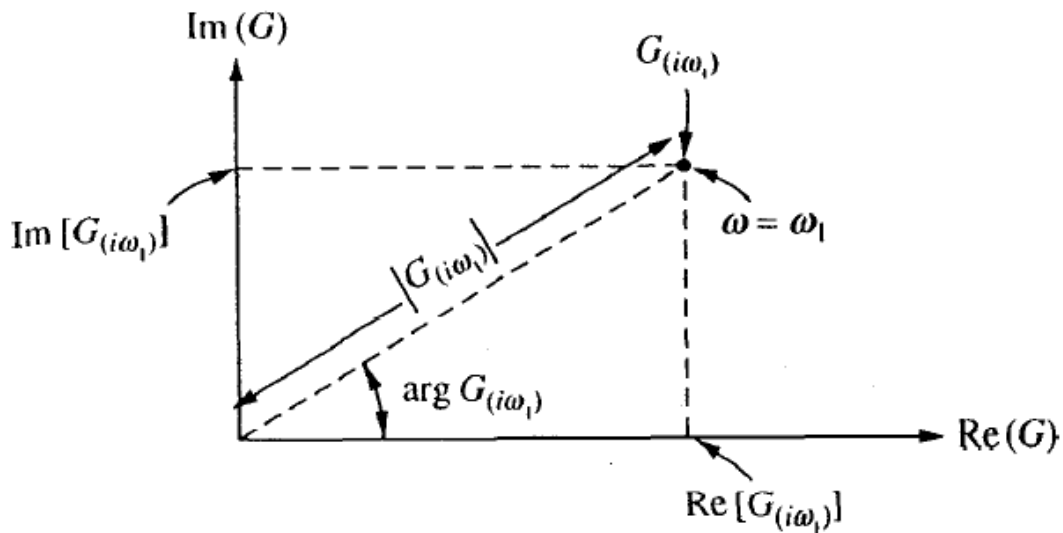
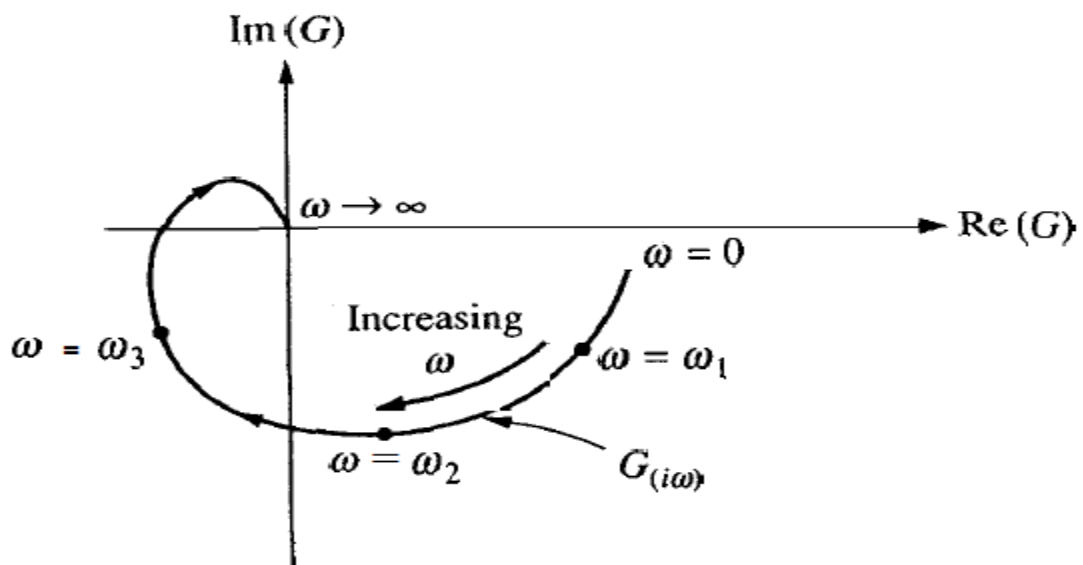


Nyquist diagram

$$G(s), s = j\omega$$

$$G(j\omega) = R + jI$$

$$R = f(\omega), I = f(\omega)$$

Fig.56 Nyquist diagram in G plane for single point $G(j\omega_1)$ Fig.57 Nyquist diagram in G plane for complete curve $G(j\omega)$

1st order system

$$G(s) = \frac{k}{\tau s + 1}$$

$$s = j\omega$$

$$G(j\omega) = \frac{k}{\tau j\omega + 1}$$

$$G(j\omega) = \frac{k}{\tau j\omega + 1} \times \frac{\tau j\omega - 1}{\tau j\omega - 1}$$

$$G(j\omega) = \frac{k}{\tau^2 \omega^2 + 1} - j \frac{k\omega\tau}{\tau^2 \omega^2 + 1}$$

$$|G| = \frac{k}{\sqrt{\tau^2 \omega^2 + 1}}$$

$$\angle G = -\tan^{-1} \omega\tau$$

$$R = \frac{1}{\tau^2 \omega^2 + 1}, I = \frac{-k\omega\tau}{\tau^2 \omega^2 + 1}$$

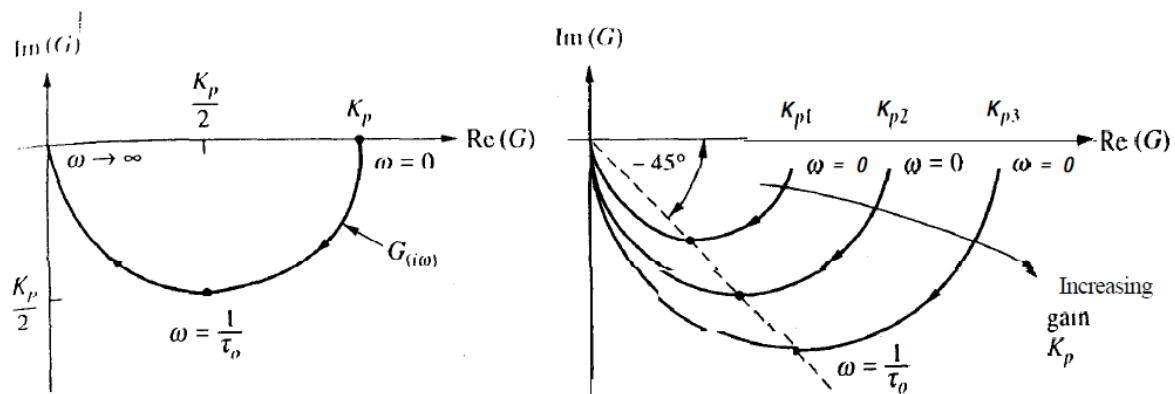


Fig.58

Nyquist diagram of first-order system

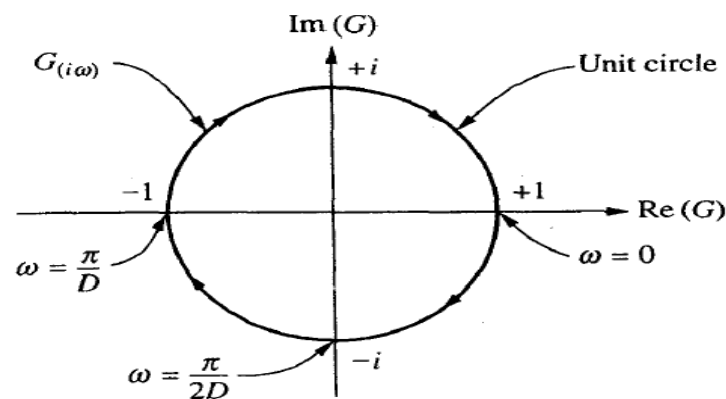


Fig.59 Nyquist diagram of dead time, (time delay)

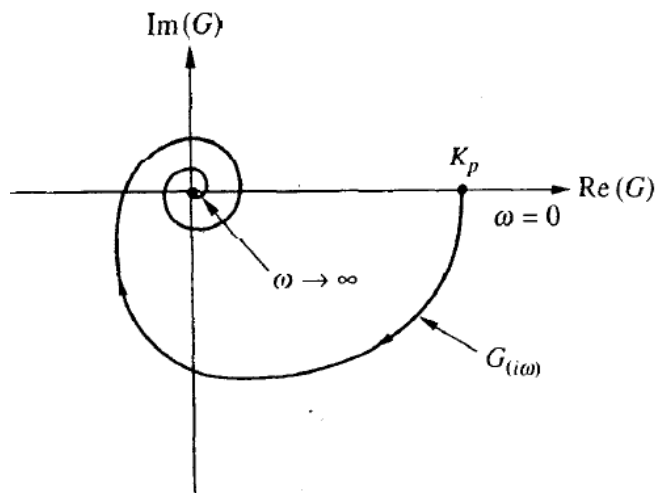


Fig.60 Nyquist diagram of first-order with time delay.

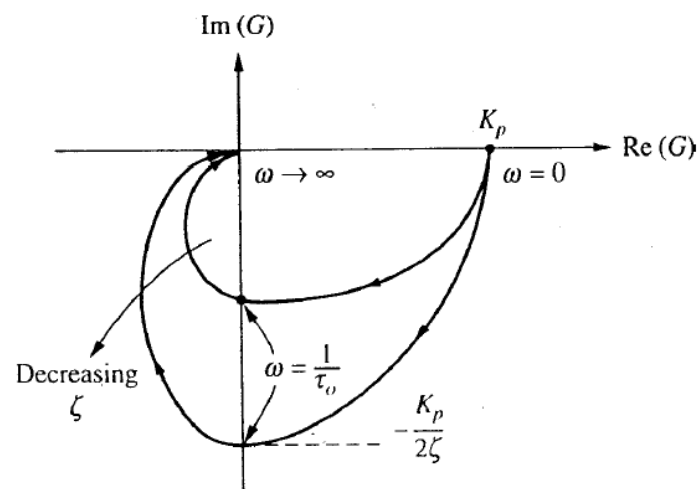


Fig.61 Nyquist diagram of second-order.