

**Heating tank**

c.  $\theta_o = f(m(s))$ :  $m$  is changed while  $\theta_i$  and  $q$  are remained constant at their initial steady-state values

$$\theta_o = f(m(s))$$

$$G_3(s) = \frac{\theta_o(s)}{m(s)}$$

**1. Steady state head balance :**

Heat in by flow + heat out by heat transfer - heat out by flow = Heat accumulation

$$m^o C_p \theta_i^o + q^o - m^o C_p \theta_o^o = M C_p \frac{d\theta_o^o}{dt} = 0 \quad (1)$$

**2. Transient state:**

$$m(t) C_p \theta_i^o + q^o - m(t) C_p \theta_o(t) = M C_p \frac{d\theta_o(t)}{dt} \quad (2)$$

**Linearization :**

Eq. (2) is a nonlinear D.E. due to the nonlinear form term  $m(t) C_p \theta_o(t)$ . this form should be linearized around  $m^o$  and  $\theta_o^o$ .

$$f(m, \theta_o) = f(m^o, \theta_o^o) + \left[ \frac{\partial f}{\partial m} \right]_{(m^o, \theta_o^o)} (m - m^o) + \left[ \frac{\partial f}{\partial \theta_o} \right]_{(m^o, \theta_o^o)} (\theta_o - \theta_o^o)$$

$$f(m, \theta_o) = m(t) C_p \theta_o(t)$$

$$\left[ \frac{\partial f}{\partial m} \right]_{(m^o, \theta_o^o)} = C_p \theta_o^o \quad \text{and} \quad \left[ \frac{\partial f}{\partial \theta_o} \right]_{(m^o, \theta_o^o)} = C_p \theta_i^o$$

$$f(m(t), \theta_o(t)) \approx m^o C_p \theta_i^o + C_p \theta_o^o (m(t) - m^o) + C_p \theta_i^o (\theta_o(t) - \theta_o^o)$$

After linearization, Eq.2 becomes:

$$m(t) C_p \theta_i^o + q^o - \left( m^o C_p \theta_i^o + C_p \theta_o^o (m(t) - m^o) + C_p \theta_i^o (\theta_o(t) - \theta_o^o) \right) = M C_p \frac{d\theta_o(t)}{dt} \quad (3)$$

Eq.4 is linear, first order differential equation and zero initial condition

Subtracting Eq.1 from Eq. 3 :

$$m(t) C_p \theta_i^o - m^o C_p \theta_o(t) - \theta_o^o C_p m(t) = M C_p \frac{d\theta_o(t)}{dt} \quad (4)$$

Eq.4 is linear, first order differential equation and zero initial condition

$$MC_p \frac{d\theta_o(t)}{dt} + m^o C_p \theta_o(t) = C_p (\theta_i^o - \theta_o^o) m(t)$$

$$\left(\frac{M}{m^o}\right) \frac{d\theta_o(t)}{dt} + \theta_o(t) = -\frac{(\theta_o^o - \theta_i^o)}{m^o} m(t)$$

$$\tau \frac{d\theta_o(t)}{dt} + \theta_o(t) = -K_P m(t)$$

$$G(s) = \frac{\theta_o(s)}{\theta_i(s)} = -\frac{K_P}{\tau s + 1}$$

$$\theta_o(t) = -K_P (1 - e^{-t/\tau})$$

$\theta_i$  and  $q$  are changed while  $m$  remained constant at their initial steady state

Steady state heat balance:

$$m^o C_p \theta_i^o + q^o - m^o C_p \theta_o^o = MC_p \frac{d\theta_o^o}{dt} = 0 \quad (1)$$

Unsteady state heat balance:

$$m^o C_p \theta_i'(t) + q'(t) - m^o C_p \theta_o'(t) = MC_p \frac{d\theta_o'(t)}{dt} \quad (2)$$

Subtracting Eq.1 from Eq.2:

$$m^o C_p (\theta_i'(t) - \theta_i^o) + q^o - q'(t) - m^o C_p (\theta_o'(t) - \theta_o^o) = MC_p \frac{d(\theta_o'(t) - \theta_o^o)}{dt}$$

$$m^o C_p \theta_i(t) + q(t) - m^o C_p \theta_o(t) = MC_p \frac{d\theta_o(t)}{dt}$$

$$\tau \frac{d\theta_o(t)}{dt} + \theta_o(t) = \theta_i(t) + \frac{1}{m^o C_p} q(t) \quad (3)$$

Taking Laplace transform of Eq.3:

$$(\tau s + 1) \theta_o(s) = K_1 \theta_i(s) + K_2 q(s)$$

$$\theta_o(s) = \frac{K_1}{\tau s + 1} \theta_i(s) + \frac{K_2}{\tau s + 1} q(s)$$

Step change in  $\theta_i(t)$  of  $\theta_i$  and  $q(t)$  of  $q$

$$\theta_o(s) = \frac{K_1}{\tau s + 1} \frac{\theta_i}{s} + \frac{K_2}{\tau s + 1} \frac{q}{s}$$

$$\theta_o(t) = (K_1\theta_i + K_2q) \left(1 - e^{-t/\tau}\right)$$