

Q.1 - Complete the following sentences.

1- A linear time invariant system initially at rest, when subjected to a unit-step input gives a response  $y(t) = 0.3333 + 0.1667e^{-3t} - 0.5e^{-t}$ . The transfer function of the system is \_\_\_\_\_

[2 Marks]

2- The transfer function of a control system is given as;  $G(S) = \frac{K}{(s^2 + 8s + K)}$ . For this system to be critically damped, the value of K should be \_\_\_\_\_.

[2 marks]

3- For a second order system, if both the roots of the characteristic equation are real and equal then the value of damping ratio will be \_\_\_\_\_.

[2 marks]

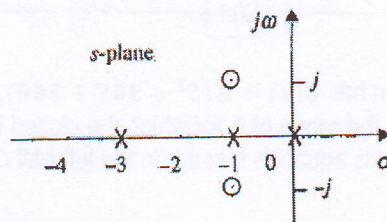
4- The first element of each of the rows of a Routh-Hurwitz stability test showed the sign as follows

| Rows  | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|-------|---|---|---|---|---|---|---|---|---|
| Signs | + | - | - | - | + | - | + | - | - |

The number of roots of the system lying in the right half of s-plane is \_\_\_\_\_ and the system is \_\_\_\_\_

[2 marks]

5 - The pole-zero configuration for a control system shown in figure below



The intersection of asymptotes with the real axis is \_\_\_\_\_.

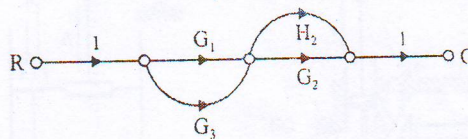
[2 marks]

6- The equation governing a control system is given by  $3 \frac{d^2 c(t)}{dt^2} + \frac{12 dc(t)}{dt} + 32c(t) = 32r(t)$ . The transfer function for the system is \_\_\_\_\_.

[2 marks]

7- The number of closed loops and forward paths in the signal flow graph shown below is \_\_\_\_\_ and \_\_\_\_\_.

[2 Marks]



8 - Match list A with list B.

[2 marks]

| List A (characteristic equation) | List B (Natural of damping) |
|----------------------------------|-----------------------------|
| A - $S^2 + 15S + 26.25$          | 1- un damped .              |
| B - $S^2 + 5S + 6.25$            | 2- under damped.            |
| C - $S^2 + 20.25$                | 3- critically damped.       |
| D - $S^2 + 4.5S + 42.45$         | 4- over damped.             |

9- what is the advantage and disadvantage of the open loop control system .

[2 marks]

10 - Sketch a typical transient response of a second order control system in cases of under damped for  
i- Stable control system    ii- Unstable control system.

[2 marks]

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Page (1 of 2)

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